Effect handler oriented programming

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NTU Singapore, November 2024

What is an effect?



Programs as black boxes (Church-Turing model)?



Effects

Programs must interact with their environment



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Effects

Programs must interact with their environment



Effects are pervasive

- input/output user interaction
- concurrency web applications
- distribution cloud computing
- exceptions fault tolerance
- choice backtracking search

Typically ad hoc and hard-wired



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Handlers of algebraic effects, ESOP 2009 (and ETAPS 2022 test of time award)



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Monads \longrightarrow Algebraic Effects \longrightarrow Effect Handlers



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 $\mathsf{Monads} \longrightarrow \mathsf{Algebraic} \ \mathsf{Effects} \longrightarrow \mathsf{Effect} \ \mathsf{Handlers}$

Composable and customisable user-defined interpretation of effects in general



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Composable and customisable user-defined interpretation of effects in general

Give programmer direct access to **context** (c.f. resumable exceptions, monads, delimited control)



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Composable and customisable user-defined interpretation of effects in general

Give programmer direct access to **context** (c.f. resumable exceptions, monads, delimited control)

Effect handlers in practice:

OCaml 5, GitHub (Semantic), Meta (React), Uber (Pyro), Wasm (WasmFX), ...

Effect handlers as composable user-defined operating systems



Effect handlers as composable user-defined operating systems



Effect handlers for operating systems

EIO — effects-based direct-style concurrent I/O stack for OCaml https://github.com/ocaml-multicore/eio

Composing UNIX with effect handlers

Foundations for programming and implementing effect handlers, Chapter 2 Daniel Hillerström, PhD thesis, The University of Edinburgh, 2022 https://www.dhil.net/research/papers/thesis.pdf

$$\{$$
choose : 1 \rightarrow Bool, fail : $a.1 \rightarrow a\}$

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}

Coin tossing

toss : $1 \rightarrow \text{Toss!}(E \uplus \{\text{choose} : 1 \rightarrow \text{Bool}\})$ toss () = **if** choose () **then** Heads **else** Tails

```
{choose : 1 \rightarrow Bool, fail : a.1 \rightarrow a}
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Coin tossing

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toss : 1 \rightarrow \text{Toss!}(E \uplus \{\text{choose} : 1 \twoheadrightarrow \text{Bool}\})
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```
\begin{array}{l} \mathsf{drunkToss}: 1 \to \mathsf{Toss!}(E \uplus \{\mathsf{choose}: 1 \twoheadrightarrow \mathsf{Bool}, \ \mathsf{fail}: a.1 \twoheadrightarrow a\}) \\ \mathsf{drunkToss}() = \mathbf{if} \ \mathsf{choose}() \ \mathbf{then} \\ & \mathbf{if} \ \mathsf{choose}() \ \mathbf{then} \ \mathsf{Heads} \ \mathbf{else} \ \mathsf{Tails} \\ & \mathbf{else} \\ & \mathsf{fail}() \end{array}
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```

 $\begin{array}{l} \mathsf{drunkTosses}: \mathsf{Nat} \to \mathsf{List Toss!}(E \uplus \{\mathsf{choose}: 1 \twoheadrightarrow \mathsf{Bool}, \ \mathsf{fail}: a.1 \twoheadrightarrow a\}) \\ \mathsf{drunkTosses} \ n = \mathbf{if} \ n = 0 \ \mathbf{then} \ [] \\ \quad \mathbf{else} \ \mathsf{drunkTosses} \ () :: \mathsf{drunkTosses} \ (n-1) \end{array}$

Handlers

Handlers

maybeFail : $A!(E \uplus \{ \text{fail} : a.1 \rightarrow a \}) \Rightarrow Maybe A!E$ maybeFail = -exception handler**return** $x \mapsto Just x$ handle 42 with maybeFail \implies Just 42 **handle** fail () with maybeFail \implies Nothing $\langle fail() \rangle \mapsto Nothing$ trueChoice : $A!(E \uplus \{\text{choose} : 1 \twoheadrightarrow \text{Bool}\}) \Rightarrow A!E$ trueChoice = - linear handlerhandle 42 with trueChoice \implies 42 return $x \mapsto x$ $(\text{choose}() \rightarrow r) \mapsto r \text{true}$ handle toss () with trueChoice \implies Heads allChoices : $A!(E \uplus \{ choose : 1 \twoheadrightarrow Bool \}) \Rightarrow List A!E$ allChoices = --- non-linear handler return $x \mapsto [x]$ $\langle \text{choose}() \rightarrow r \rangle \mapsto r \text{ true} + r \text{ false}$

Handlers

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Handler composition

handle (handle drunkTosses 2 with maybeFail) with allChoices

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handle (handle drunkTosses 2 with allChoices) with maybeFail : Maybe (List (List Toss)) \implies Nothing

Operational semantics (deep handlers)

Reduction rules

$$\begin{array}{l} \text{let } x = V \text{ in } N \rightsquigarrow N[V/x] \\ \text{handle } V \text{ with } H \rightsquigarrow N[V/x] \\ \text{handle } \mathcal{E}[\text{op } V] \text{ with } H \rightsquigarrow N_{\text{op}}[V/p, (\lambda x.\text{handle } \mathcal{E}[x] \text{ with } H)/r], \quad \text{op } \# \mathcal{E} \end{array}$$

where

where
$$H = \operatorname{return} x \mapsto N$$

 $\langle \operatorname{op}_1 p \to r \rangle \mapsto N_{\operatorname{op}_1}$
 \dots
 $\langle \operatorname{op}_k p \to r \rangle \mapsto N_{\operatorname{op}_k}$

Evaluation contexts

$$\mathcal{E} ::= [] | \text{let } x = \mathcal{E} \text{ in } N | \text{handle } \mathcal{E} \text{ with } H$$

Typing rules (deep h	andlers)	
Effects	$E ::= \emptyset \mid E \uplus \{ op :$	$A \twoheadrightarrow B$
Computations		
	C, D ::= A!	E
Operations	$\Gamma \vdash V : A$	
	$\Gamma \vdash op \ V : B! (E \uplus \{op$	$(A \twoheadrightarrow B)$
Handlers	$\Gamma \vdash M : C \qquad \Gamma \vdash H$	$I: C \Rightarrow D$
	$\Gamma \vdash$ handle M wit	h <i>H</i> : <i>D</i>
$\Gamma, x : A \vdash N : D$	$[op_i: A_i \twoheadrightarrow B_i \in E]_i$	$[\Gamma, p: A_i, r: B_i \to D \vdash N_i: D]_i$
	$ abla \mapsto egin{array}{c} return \ x \mapsto N \ (\langle op_i \ p o r angle \mapsto N_i) \end{array}$	$A!E \Rightarrow D$

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Lifects	$E ::= \emptyset \mid E \uplus \{ op : A \twoheadrightarrow B \}$
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	C, D ::= A!E
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	$\Gamma \vdash op \ V : B! (E \uplus \{op : A \twoheadrightarrow B\})$
Handlers	$\Gamma \vdash M : C \qquad \Gamma \vdash H : C \Rightarrow D$
	$\Gamma \vdash$ handle <i>M</i> with <i>H</i> : <i>D</i>
$\Gamma, x : A \vdash N : D$	$[op_i: A_i \twoheadrightarrow B_i \in E]_i$ $[\Gamma, p: A_i, r: B_i \to D \vdash N_i: D]_i$
	$\Gamma \vdash \frac{return \ x \mapsto N}{(\langle op_i \ p \to r \rangle \mapsto N_i)_i} : A! E \Rightarrow D$

Exercise: Adapt the typing rules to accommodate parametric operations

► A modular interpreter for effectful computations

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- A generalisation of an exception handler
 - based on exceptional syntax [Benton and Kennedy, 2001]

```
let x = (try \ M \text{ with } H) in Nconventional exception handlers\downarrow\downarrowexceptional syntax\downarrow\downarroweffect handlers
```

success continuations aid composition, optimisation, and reasoning resumable

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success continuations aid composition, optimisation, and reasoning resumable

- A morphism between (free) algebras
- ► A fold (catamorphism) over a command-response tree
- A structured delimited control operator
- A composable user-defined operating system

 $\{\texttt{send}:\mathsf{Nat}\twoheadrightarrow 1\}$

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A simple generator

```
nats : Nat \rightarrow 1! (E \uplus \{\text{send} : \text{Nat} \twoheadrightarrow 1\})
nats n = \text{send } n; nats (n + 1)
```

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A simple generator

nats : Nat
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Handler — function that returns a handler

until : Nat $\rightarrow 1!(E \uplus \{\text{send} : \text{Nat} \twoheadrightarrow 1\}) \Rightarrow \text{List Nat}!E$ until stop =return () \mapsto [] $\langle \text{send } n \rightarrow r \rangle \mapsto \text{if } n < stop \text{ then } n :: r ()$ else []

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handle nats 0 with until 8 \implies [0, 1, 2, 3, 4, 5, 6, 7]

Effect signature

 $\{ \textit{yield} : 1 \twoheadrightarrow 1 \}$

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$$\{\mathsf{yield}: \mathbf{1} \twoheadrightarrow \mathbf{1}\}$$

Two cooperative lightweight threads

Types

Thread
$$E = 1 \rightarrow 1! (E \uplus {\text{yield} : 1 \twoheadrightarrow 1})$$

Handler — recursive function containing a shallow handler

```
cooperate : List (Thread E) \rightarrow 1!E
cooperate [] = ()
cooperate (t :: ts) =
handle<sup>†</sup> t() with
return () \mapsto cooperate (ts)
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```

```
cooperate [tA, tB] \implies ()
A1 B1 A2 B2
```

Operational semantics (shallow handlers)

Reduction rules

$$\begin{array}{l} \text{let } x = V \text{ in } N & \rightsquigarrow N[V/x] \\ \text{handle}^{\dagger} V \text{ with } H & \rightsquigarrow N[V/x] \\ \text{handle}^{\dagger} \mathcal{E}[\text{op } V] \text{ with } H & \rightsquigarrow N_{\text{op}}[V/p, (\lambda x. \mathcal{E}[x])/r], \quad \text{op } \# \mathcal{E} \end{array}$$

where
$$H = \operatorname{return} x \mapsto N$$

 $\langle \operatorname{op}_1 p \to r \rangle \mapsto N_{\operatorname{op}_1}$
 \dots
 $\langle \operatorname{op}_k p \to r \rangle \mapsto N_{\operatorname{op}_k}$

Evaluation contexts

$$\mathcal{E} ::= [] | \text{let } x = \mathcal{E} \text{ in } N | \text{handle}^{\dagger} \mathcal{E} \text{ with } H$$

Typing rules (shallow	handlers)
Effects	$E ::= \emptyset \mid E \uplus \{ op : A \twoheadrightarrow B \}$
Computations	C, D ::= A!E
Operations	$\frac{\Gamma \vdash V : A}{\Gamma \vdash op \ V : B! (E \uplus \{op : A \twoheadrightarrow B\})}$
Handlers	$\frac{\Gamma \vdash M : C}{\Gamma \vdash \text{handle}^{\dagger} M \text{ with } H : D}$
$\Gamma, x : A \vdash N : D$	$[op_i : A_i \twoheadrightarrow B_i \in E]_i \qquad [\Gamma, p : A_i, r : B_i \to A!E \vdash N_i : D]_i$ $\Gamma \vdash \underset{(I = n = i}{\operatorname{return}} x \mapsto N \qquad : A!E \Rightarrow^{\dagger} D$
	$(\langle op_i \ p \to r \rangle \mapsto w_i)_i$

Effect signature — recursive effect signature

 $\mathsf{Coop}\ E = E \uplus \{\mathsf{yield} : 1 \twoheadrightarrow 1, \ \mathsf{fork} : (1 \to 1!\mathsf{Coop}\ E) \twoheadrightarrow 1\}$

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A single cooperative program

```
 \begin{array}{l} \text{main}: 1 \rightarrow 1! \text{Coop } E \\ \text{main} () = \text{print "M1 "; fork } (\lambda().\text{print "A1 "; yield } (); \text{print "A2 "}); \\ \text{print "M2 "; fork } (\lambda().\text{print "B1 "; yield } (); \text{print "B2 "}); \\ \text{print "M3 "} \end{array}
```

Types

Thread $E = 1 \rightarrow 1!$ Coop E

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cooperate [main] \Longrightarrow ()
M1 A1 M2 B1 A2 M3 B2
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Built-in effects

Output

$$\mathsf{Output} = \{\mathsf{print} : \mathsf{String} \twoheadrightarrow 1\}$$

Generative state

$$\begin{aligned} \mathsf{GenState} &= \{ \mathsf{new} \ : a. & a \twoheadrightarrow \mathsf{Ref} a, \\ & \mathsf{write} : a. \ (\mathsf{Ref} \ a \times a) \twoheadrightarrow 1, \\ & \mathsf{read} \ : a. & \mathsf{Ref} \ a \twoheadrightarrow a \} \end{aligned}$$

Example 5: actors Process ids

$$\mathsf{Pid}\ a = \mathsf{Ref}\ (\mathsf{List}\ a)$$

Effect signature

Actor
$$a = \{ self : 1 \twoheadrightarrow Pid a, spawn : b. (1 \rightarrow 1!Actor b) \twoheadrightarrow Pid b, send : b. (b \times Pid b) \twoheadrightarrow 1, recv : 1 \twoheadrightarrow a \}$$

Example 5: actors Process ids

 $\operatorname{Pid} a = \operatorname{Ref} (\operatorname{List} a)$

Effect signature

Actor
$$a = \{ self : 1 \rightarrow Pid a, spawn : b. (1 \rightarrow 1!Actor b) \rightarrow Pid b, send : b. (b \times Pid b) \rightarrow 1, recv : 1 \rightarrow a \}$$

An actor chain

spawnMany : Pid String \rightarrow Int \rightarrow 1!($E \uplus$ Actor String) spawnMany p 0 = send ("ping!", p) spawnMany p n = spawnMany (spawn (λ ().let s = recv () in print "."; send (s, p))) (n - 1)

chain : Int $\rightarrow 1!(E \uplus \text{Actor String} \uplus \text{Output})$ chain n = spawnMany(self()) n; let s = recv() in print s Example 5: actors — via cooperative concurrency

act : Pid $a \rightarrow (1 \rightarrow 1! (E \uplus \text{Actor } a)) \rightarrow 1! \text{Coop} (E \uplus \text{GenState})$ act mine $t = handle^{\dagger} t$ () with \mapsto () return() $\langle self() \rightarrow r \rangle \qquad \mapsto act mine(\lambda(), r mine)$ $\langle \text{spawn } you \rightarrow r \rangle \qquad \mapsto \text{let } yours = \text{new [] in}$ fork (λ ().act yours (you ())); act mine (λ ().r yours) $(\text{send}(m, yours) \rightarrow r) \mapsto \text{let } ms = \text{read yours in}$ write (vours, ms ++ [m]); act mine r $(\operatorname{recv}() \rightarrow r) \mapsto \operatorname{letrec} \operatorname{recv}WhenReady() =$ case read mine of \mapsto yield (); recvWhenReady () Π $(m::ms) \mapsto write(mine, ms); act mine(\lambda(), rm)$ in recvWhenReady ()

Example 5: actors — via cooperative concurrency

 $\mathsf{cooperate}\left[\mathsf{act}\left(\mathsf{new}\left[\right]\right)\left(\lambda(\mathsf{)}.\mathsf{chain}\,\mathsf{64}\right)\right] \Longrightarrow$

Example 5: actors — via cooperative concurrency

cooperate [act (new []) (
$$\lambda$$
().chain 64)] \Longrightarrow ()
ping!

Effect handler oriented programming languages

Eff	https://www.eff-lang.org/
Effekt	https://effekt-lang.org/
Frank	https://github.com/frank-lang/frank
Helium	https://bitbucket.org/pl-uwr/helium
Links	https://www.links-lang.org/
Koka	https://github.com/koka-lang/koka
OCaml 5	https://github.com/ocamllabs/ocaml-multicore/wiki
Unison	https://www.upison.long.org/

Expressiveness

Local transformations (with Yannick Forster, Ohad Kammar, Matija Pretnar) "On the expressive power of user-defined effects: effect handlers, monadic reflection, delimited control", JFP 2019

Asymptotic complexity (with Daniel Hillerström, John Longley) "Asymptotic speedup via effect handlers", JFP 2024

Higher-order effects

(with Cristina Matache, Sean Moss, Sam Staton, Nicolas Wu, Zhixuan Yang) "Scoped effects as parameterised algebraic theories", ESOP 2024 Effect handlers for imperative languages

C++ (with Dan Ghica, Maciej Piróg, Marcello Maroñas Bravo) "High-level effect handlers in C++", OOPSLA 2022

WebAssembly (with Arjun Guha, Daniel Hillerström, Daan Leijen, Luna Phipps-Costin, Matija Pretnar, Andreas Rossberg, KC Sivaramakrishnan) "Continuing WebAssembly with effect handlers", OOPSLA 2023

С

(with Mario Alvarez-Picallo, Teodoro Freund, Dan Ghica) "Effect handlers for C via coroutines", OOPSLA 2024

Effect type systems

Frank

(with Lukas Convent, Conor McBride, Craig McLaughlin) "Doo Bee Doo Bee Doo", JFP 2020

Combining linear resources with effect handlers (with Daniel Hillerström, J. Garrett Morris, Wenhao Tang) "Soundly handling linearity", POPL 2024

Modal effect types (with Stephen Dolan, Daniel Hillerström, Anton Lorenzen, Wenhao Tang, Leo White) "Modal effect types", arXiv 2024 EPOCH: Effectful Programming on Capability Hardware (with Ian Stark, Brian Campbell, Wilmer Ricciotti) funded by Edinburgh-Huawei joint Iab

UCFX: Universal Composability with Effects and Handlers (with Markulf Kohlweiss, Danel Ahman, Pooya Farshim, Sabine Oeschner, Jesse Sigal) funded by Input Output Research Hub

Resources



Jeremy Yallop's effects bibliography https://github.com/yallop/effects-bibliography



Matija Pretnar's tutorial "An introduction to algebraic effects and handlers", MFPS 2015



Andrej Bauer's tutorial "What is algebraic about algebraic effects and handlers?", OPLSS 2018



Daniel Hillerström's PhD thesis "Foundations for programming and implementing effect handlers", 2022