

Parameterized algebraic theories and applications

Cristina Matache

University of Edinburgh

Introduction: algebraic effects

Side effects (e.g. I/O, state, nondeterminism) in functional languages can be modelled using:

- ▶ **monads** [Moggi'91] E.g. monads in Haskell;
- ▶ or using **algebraic theories** [Plotkin&Power]:
 - operations (e.g. reading and writing to memory) produce the effects;
 - program equations specify the behaviour of operations.

There is a correspondence between strong **monads** and **algebraic theories**.

Introduction: algebraic effects

Some effects do not fit into this algebraic framework.

Examples: dynamically allocating new memory locations, exception catching, continuations, normalizing a probability distribution, measuring qubits etc.

The following frameworks capture some of these effects:

- ▶ **Scoped effects** [Wu et. al.'14].
- ▶ **Parameterized algebraic theories** [Staton'13].

Contributions

- ▶ Scoped effects as parameterized theories [Lindley, Matache, Moss, Staton, Wu, Yang ESOP'24].
- ▶ Work in progress towards a parameterized theory of Unix fork.

Outline

- 1 Algebraic effects and algebraic theories
- 2 Parameterized algebraic theories
- 3 Scoped effects
- 4 Scoped effects as parameterized algebraic theories
- 5 A parameterized theory of threads (work in progress)

Example: explicit nondeterminism (backtracking) [Plotkin&Pretnar'09, '13]

Operations

`or(x, y)` choice

`fail` failure

Equations

$x, y, z \vdash \text{or}(x, \text{or}(y, z)) = \text{or}(\text{or}(x, y), z)$

$x \vdash \text{or}(\text{fail}, x) = \text{or}(x, \text{fail}) = x$

In direct style:

or : unit \rightarrow bool

bool = arity

unit = coarity

fail : unit \rightarrow 0

Translation between direct style and algebraic operations:

$\text{or}(x, y) = \text{if } \underline{\text{or}}() \text{ then } x \text{ else } y$

$\underline{\text{or}}() = \text{or}(\text{true}, \text{false})$

Example: explicit nondeterminism (backtracking) [Plotkin&Pretnar'09, '13]

Operations

`or`(x, y) choice

`fail` failure

Equations

$$x, y, z \vdash \text{or}(x, \text{or}(y, z)) = \text{or}(\text{or}(x, y), z)$$

$$x \vdash \text{or}(\text{fail}, x) = \text{or}(x, \text{fail}) = x$$

Model = a set (carrier) + interpretations for the operations.

Fix a set A . The intended model for the theory of nondeterminism is:

- ▶ Carrier: the set $\text{List}(A)$
- ▶ Operations:

$$\llbracket \text{or} \rrbracket : \text{List}(A)^2 \rightarrow \text{List}(A),$$

$$\llbracket \text{fail} \rrbracket : 1 \rightarrow \text{List}(A),$$

$$\llbracket \text{or} \rrbracket (l_1, l_2) = l_1 @ l_2$$

$$\llbracket \text{fail} \rrbracket () = []$$

Example: one-bit state

Operations

$\text{put}(i; x)$, $i \in \mathbb{Z} = \{0, 1\}$ writing
 $\text{get}(x_0, x_1)$ reading

Equations

$x_0, x_1 \vdash \text{put}(i; \text{get}(x_0, x_1)) = \text{put}(i; x_i)$
 $x \vdash \text{put}(i; \text{put}(i'; x)) = \text{put}(i'; x)$
 $x \vdash \text{get}(\text{put}(0; x), \text{put}(1; x)) = x$

In direct style:

put : bool \rightarrow unit

get : unit \rightarrow bool

unit = arity

bool = coarity

Example: one-bit state

Operations

$\text{put}(i; x)$, $i \in \mathcal{2} = \{0, 1\}$ writing
 $\text{get}(x_0, x_1)$ reading

Equations

$$\begin{aligned}x_0, x_1 \vdash \text{put}(i; \text{get}(x_0, x_1)) &= \text{put}(i; x_i) \\x \vdash \text{put}(i; \text{put}(i'; x)) &= \text{put}(i'; x) \\x \vdash \text{get}(\text{put}(0; x), \text{put}(1; x)) &= x\end{aligned}$$

Fix a set A . The intended **model** for the algebraic theory of state is:

- ▶ Carrier: $(A \times \mathcal{2})^2$
- ▶ Operations:

$$\llbracket \text{put} \rrbracket : \mathcal{2} \times (A \times \mathcal{2})^2 \rightarrow (A \times \mathcal{2})^2$$

$$\llbracket \text{put} \rrbracket(i, f) = \lambda b. f(i)$$

$$\llbracket \text{get} \rrbracket : (A \times \mathcal{2})^2 \times (A \times \mathcal{2})^2 \rightarrow (A \times \mathcal{2})^2$$

$$\llbracket \text{get} \rrbracket(f_0, f_1) = \lambda b. \begin{cases} (f_0 b) & \text{if } b = 0 \\ (f_1 b) & \text{if } b = 1 \end{cases}$$

Algebraic theories

- ▶ Algebraic theories provide an **equational reasoning system** for algebraic effects, with semantic **models**, such that equality in the theory is **sound and complete**.
- ▶ $\text{List}(A)$ and $(A \times \mathbb{2})^2$ are **free models** on the set A .
- ▶ List and $(- \times \mathbb{2})^2$ extend to strong monads on Set . Used for implementation and denotational semantics.
- ▶ Correspondence between **algebraic theories** and finitary (strong) **monads** on Set , via the free model construction.

Outline

- 1 Algebraic effects and algebraic theories
- 2 Parameterized algebraic theories**
- 3 Scoped effects
- 4 Scoped effects as parameterized algebraic theories
- 5 A parameterized theory of threads (work in progress)

Parameterized theory example: local state

Local state = dynamically creating memory locations that store one bit

Parameters = **location names**

put($a, i; x$) write value $i \in \{0, 1\}$ to location a , continue as x ;
 a is a free parameter

get($a; x_0, x_1$) read the bit stored in location a and continue as
either x_0 or x_1 ; a is a free parameter

new($i; a.x(a)$) create a new location a , containing $i \in \{0, 1\}$
 a is a fresh parameter, bound

+ operation for equality testing and equations [Staton LICS'13]

Parameterized theory example: local state

Parameters = **location names**

\mathbb{P} = **abstract** type of parameters

In direct style:

put($a, i; x$) put : $\mathbb{P} \times \text{bool} \rightarrow \text{unit}$

get($a; x_0, x_1$) get : $\mathbb{P} \rightarrow \text{bool}$

new($i; a.x(a)$) new : $\text{bool} \rightarrow \mathbb{P}$ $\mathbb{P} = \text{arity}$ $\text{bool} = \text{coarity}$

For algebraic theories, arities and coarities are sums of **unit**. Now we allow sums and products with \mathbb{P} .

Parameterized algebraic theories [Staton FOSSACS'13, LICS'13]

- ▶ Uniform framework for axiomatizing local effects.
- ▶ Extend plain algebraic theories with **binding**.
- ▶ Provide an **equational reasoning system**, sound and complete with respect to **models**, and have a correspondence with strong monads.
- ▶ A **model** has carrier X from $\mathbf{Set}^{\mathbf{Fin}}$, where:
 - \mathbf{Fin} = natural numbers and functions between them
 - $n \in \mathbf{Ob}(\mathbf{Fin})$ = a typing context with n parameters
 - $\llbracket \mathbb{P} \rrbracket = \mathbf{Fin}(1, -)$

and interpretations for operations:

$$\text{E.g: } \llbracket \text{put} \rrbracket : X \rightarrow X^{\llbracket \mathbb{P} \rrbracket \times 2} \quad \llbracket \text{get} \rrbracket : X^2 \rightarrow X^{\llbracket \mathbb{P} \rrbracket} \quad \llbracket \text{new} \rrbracket : X^{\llbracket \mathbb{P} \rrbracket} \rightarrow X^2$$

Parameterized algebraic theories [Staton FOSSACS'13, LICS'13, POPL'15]

Example	Parameters	Models in
name generation	names	Set^{Fin}
local state	location names	
π -calculus (fragment)	communication channels	
first-order logic	individuals	
quantum computation	qubits (linear)	Set^{Bij}
scoped effects <small>[ESOP'24]</small>	scopes (ordered, linear)	$\text{Set}^{ \mathbb{N} }$
Unix fork (work in progress)	thread IDs	Set^{Fin}

For each of these functor categories: **parameterized theories** correspond to sifted-colimit-preserving strong **monads**. [Lack & Rosicky'11, *Notions of Lawvere theories*]

Outline

- 1 Algebraic effects and algebraic theories
- 2 Parameterized algebraic theories
- 3 Scoped effects**
- 4 Scoped effects as parameterized algebraic theories
- 5 A parameterized theory of threads (work in progress)

Example: explicit nondeterminism with once [Wu et. al.'14]

Operations:

`or`(x, y) choice

`fail` failure

`once`(x) choose the first non-failing result of x

The **free model** uses the `List` monad. For a set A :

$$\llbracket \text{or} \rrbracket : \text{List}(A)^2 \rightarrow \text{List}(A), \quad \llbracket \text{or} \rrbracket (l_1, l_2) = l_1 @ l_2$$

$$\llbracket \text{fail} \rrbracket : 1 \rightarrow \text{List}(A), \quad \llbracket \text{fail} \rrbracket () = []$$

We want the interpretation of `once` to be:

$$\llbracket \text{once} \rrbracket : \text{List}(A) \rightarrow \text{List}(A) \quad \llbracket \text{once} \rrbracket ([a, \dots]) = [a] \quad \llbracket \text{once} \rrbracket ([]) = []$$

Algebraicity

Operations $\llbracket \text{op} \rrbracket$ in the free model of a theory behave well with respect to the structure of the induced monad T :

$$\llbracket \text{op} \rrbracket : TA \rightarrow TA \qquad \ggg : TA \times (A \Rightarrow TB) \rightarrow TB$$

$$(\llbracket \text{op} \rrbracket(x) \ggg \lambda a. y) = \llbracket \text{op} \rrbracket(x \ggg \lambda a. y)$$

Example:

$$\llbracket \text{or} \rrbracket : \text{List}(\mathbb{N})^2 \rightarrow \text{List}(\mathbb{N}) \qquad \ggg : \text{List}(\mathbb{N}) \times (\mathbb{N} \Rightarrow \text{List}(\mathbb{N})) \rightarrow \text{List}(\mathbb{N})$$

$$k = \lambda n. [n, n + 1] \qquad (\llbracket \text{or} \rrbracket([1], [3]) \ggg k) = ([1, 3] \ggg k) = [1, 2, 3, 4]$$

$$\llbracket \text{or} \rrbracket([1] \ggg k, [3] \ggg k) = \llbracket \text{or} \rrbracket([1, 2], [3, 4]) = [1, 2, 3, 4]$$

Algebraicity

Operations $\llbracket \text{op} \rrbracket$ in the free model of a theory behave well with respect to the structure of the induced monad T :

$$\llbracket \text{op} \rrbracket : TA \rightarrow TA \qquad \ggg : TA \times (A \Rightarrow TB) \rightarrow TB$$

$$(\llbracket \text{op} \rrbracket(x) \ggg \lambda a. y) = \llbracket \text{op} \rrbracket(x \ggg \lambda a. y)$$

Example in direct style:

$$\underline{\text{or}} : \text{unit} \rightarrow \text{bool}$$

$$\text{if } \underline{\text{or}}() \text{ then } f(); h() \text{ else } g(); h() = (\text{if } \underline{\text{or}}() \text{ then } f() \text{ else } g()); h()$$

Algebraicity fails for once

$\llbracket \text{once} \rrbracket : \text{List}(A) \rightarrow \text{List}(A)$ is **not algebraic** with respect to the `List` monad.

Example:

$$\llbracket \text{or} \rrbracket : \text{List}(\mathbb{N})^2 \rightarrow \text{List}(\mathbb{N}) \quad \ggg : \text{List}(\mathbb{N}) \times (\mathbb{N} \Rightarrow \text{List}(\mathbb{N})) \rightarrow \text{List}(\mathbb{N})$$

$$k = \lambda n. [n, n + 1] \quad (\llbracket \text{once} \rrbracket(\llbracket \text{or} \rrbracket([1], [3]))) \ggg k = ([1] \ggg k) = [1, 2]$$

$$\llbracket \text{once} \rrbracket(\llbracket \text{or} \rrbracket([1], [3]) \ggg k) = \llbracket \text{once} \rrbracket([1, 2, 3, 4]) = [1]$$

- ▶ Intuition: the scope of `once` is delimited; `once` is a scoped effect
- ▶ **Scoped effect** = a monad on `Set` with non-algebraic operations
[Wu et. al.'14, Yang & Wu'23].
- ▶ Do (`once`, `or`, `fail`) + equations present a monad?

Scoped effects: background

- ▶ Other examples: exception catching, state with local variables.
- ▶ Scoped effects implemented as **effect handlers** [Plotkin&Pretnar'09, '13]. Not guaranteed to satisfy equations.
- ▶ Treating scoped effects as operations: work on free monads from signatures and extending effect handlers to handle scoped operations. [Wu et. al.'14], [Piróg et.al. LICS'18], [Yang et.al. ESOP'22]

Our contribution [Lindley, Matache, Moss, Staton, Wu, Yang ESOP'24]

Finding a notion of algebraic theory to axiomatize scoped effects.

Outline

- 1 Algebraic effects and algebraic theories
- 2 Parameterized algebraic theories
- 3 Scoped effects
- 4 Scoped effects as parameterized algebraic theories**
- 5 A parameterized theory of threads (work in progress)

Scoped effects as parameterized algebraic theories

Parameters = names of scopes

A scoped effect = a theory with **ordered, linear** parameters

Example: explicit nondeterminism with once

`or`(x, y) choice

`fail` failure

`once`($a.x(a)$) open a new scope named a , continue as $x(a)$; a is bound

`close`($a; y$) close the scope a , y cannot use a anymore; a is free

Closing a scope becomes an explicit operation. We write:

`once`($a.or(close(a; 1), close(a; 3))$) instead of `once`(`or`(1, 3))

Equations for explicit nondeterminism with once

Explicit nondeterminism

$$\text{or}(x, \text{or}(y, z)) = \text{or}(\text{or}(x, y), z)$$

$$\text{or}(\text{fail}, x) = \text{or}(x, \text{fail}) = x$$

We can derive:

$$\text{once}(a.\text{close}(a; x)) = x$$

We can prove using the equations:

$$\text{once}(a.\text{or}(\text{close}(a; \text{or}(1, 2)), \text{close}(a; \text{or}(3, 4)))) = \text{or}(1, 2)$$

Once/close

$$\text{once}(a.\text{fail}) = \text{fail}$$

$$\text{once}(a.\text{or}(x(a), x(a))) = \text{once}(a.x(a))$$

$$\text{once}(a.\text{or}(\text{close}(a; x), y(a))) = x$$

Models for explicit nondeterminism with once

Model = an object from $\text{Set}^{|\mathbb{N}|}$ (carrier) + interpretations for the operations.

The **free model** on $A = (A_0, \emptyset, \emptyset, \dots) \in \text{Set}^{|\mathbb{N}|}$ has:

- ▶ Carrier: the sequence $TA(n) = \text{List}^{n+1}(A_0)$, for $n \in \mathbb{N}$
- ▶ Operations:

$$\llbracket \text{once} \rrbracket_n : TA(n+1) \rightarrow TA(n) \quad \llbracket \text{once} \rrbracket_n([a, \dots]) = a, \quad \llbracket \text{once} \rrbracket_n([]) = []$$

$$\llbracket \text{close} \rrbracket_n : TA(n) \rightarrow TA(n+1) \quad \llbracket \text{close} \rrbracket_n(l) = [l]$$

$$\llbracket \text{or} \rrbracket_n : TA(n)^2 \rightarrow TA(n) \quad \llbracket \text{or} \rrbracket_n(l_1, l_2) = l_1 @ l_2$$

$$\llbracket \text{fail} \rrbracket_n : 1 \rightarrow TA(n) \quad \llbracket \text{fail} \rrbracket_n() = []$$

Recall: $\text{once}(a.x(a))$ $\text{close}(a; y)$ $\text{or}(x, y)$ fail

Scoped effects as parameterized algebraic theories

Theorem [ESOP'24]

The **free model** on $A = (A_0, \emptyset, \emptyset, \dots) \in \mathbf{Set}^{|\mathbb{N}|}$ (from previous slide) is the model for nondeterminism with once in [Piróg et.al. LICS'18].

- ▶ The model from [Piróg et.al. LICS'18] is a monad algebra, for a monad obtained from a signature of operations, with no equations.
- ▶ Therefore, we have an equational characterization of a model from the scoped effects literature.
- ▶ We have analogous results for exception catching, state with local variables, and backtracking with cut.
- ▶ Parameterized theories can axiomatize scoped effects.

Outline

- 1 Algebraic effects and algebraic theories
- 2 Parameterized algebraic theories
- 3 Scoped effects
- 4 Scoped effects as parameterized algebraic theories
- 5** A parameterized theory of threads (work in progress)

Applications of parameterized theories

Example	Parameters	Models in
name generation local state π -calculus (fragment) first-order logic	names location names communication channels individuals	Set^{Fin}
quantum computation	qubits (linear)	Set^{Bij}
scoped effects [ESOP'24] Unix fork (work in progress)	scopes (ordered, linear) thread IDs	$\text{Set}^{ \mathbb{N} }$ Set^{Fin}

I'll discuss the example of forking threads. Parameters are unconstrained.

Parameterized theory of threads with names

Parameters = thread IDs = \mathbb{P}

Operations:

`fork`($a.x(a)$, y) x = parent thread; might use a
 y = child thread; cannot use a
 a = ID of child; bound name

`wait`(a ; x) wait for the thread named a to finish, continue as x

`stop` this thread has finished (no continuation)

In direct style: `fork` : $\text{unit} \rightarrow \mathbb{P} + \text{unit}$ `wait` : $\mathbb{P} \rightarrow \text{unit}$

(Tentative) Equations for the parameterized theory of threads

Children that stop immediately:

$$x : 0 \mid - \vdash \text{fork}(a.x, \text{stop}) = x \qquad x : 0 \mid - \vdash \text{fork}(a.\text{wait}(a; x), \text{stop}) = x$$

Forking and waiting commute:

$$x : 2, y : 1 \mid b \vdash \text{fork}(a.\text{wait}(b; x(b, a)), \text{wait}(b; y(b))) = \text{wait}(b; \text{fork}(a.x(b, a), y(b)))$$

Waiting is idempotent and commutative:

$$x : 1 \mid a \vdash \text{wait}(a; \text{wait}(a; x(a))) = \text{wait}(a; x(a))$$

$$x : 2 \mid a, b \vdash \text{wait}(a; \text{wait}(b; x(a, b))) = \text{wait}(b; \text{wait}(a; x(a, b)))$$

(Tentative) Equations for the parameterized theory of threads

Forking is commutative and associative:

$$x : 2, y_1, y_2 : 0 \mid - \vdash \text{fork}(a.\text{fork}(b.x(a, b), y_2), y_1) = \text{fork}(b.\text{fork}(a.x(a, b), y_1), y_2)$$

$$x, y : 1, z : 0 \mid - \vdash \text{fork}(a.x(a), \text{fork}(b.y(b), z)) = \text{fork}(b.\text{fork}(a.x(a), y(b)), z)$$

The parent might stop before its children:

$$y : 0 \mid - \vdash \text{fork}(a.\text{stop}, y) \neq y$$

But:

$$y : 0 \mid - \vdash \text{fork}(a.\text{wait}(a; \text{stop}), y) = y$$

Parameterized theory of threads – Work in progress

- ▶ Find a nice description of the free model for this theory (without quotienting by equations), and hence of a monad.
- ▶ Compare the equations with an operational semantics for threads. Change the equations if needed.

Goal

A sound and adequate denotational semantics for Unix threads, using a monad.

Summary and future work

Summary:

- ▶ Parameterized algebraic theories extend algebraic theories with more arities (formed from an abstract type \mathbb{P}), and with binding.
- ▶ They can be used to reason equationally about:
 - scoped effects (operations that are not “algebraic”)
 - forking threads (work in progress)

Future work:

- ▶ Effect handlers for parameterized operations
- ▶ For scoped effects
 - Axiomatize more examples
 - Programming in direct style